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## Introduction to G Programming




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# Preface to an "Introduction to G Programming" 

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The Internet, personal devices and multicore computers have greatly changed and enhanced our lives by allowing us to access information and entertainment ondemand anytime, anywhere. While these technologies are great on their own merit, the reality is that in order to reap the benefits, someone has to program these devices to develop useful applications.

Historically, text-based high-level programming languages provided the first productive alternative to develop targeted applications. As more networked computing platforms enter the mainstream, the programming complexities of text based languages becomes a limiting factor, especially for domain experts who are typically not programming or computer science experts. The G programming language provides the next generation programming alternative allowing users to develop interactive parallel programs whether they have extensive programming experience or not. It's graphical syntax and constructs allow researchers, teachers, students and even children to program complex devices and systems in minutes rather than hours, days or even months.

G is a data flow graphical programming language. Originally designed to address test and measurement needs, its general purpose programming attributes has been applied in telecommunications, biomedical, aerospace, environmental and many other industries. In general, G is used in Science, Technology, Engineering and Math (STEM) projects and programs but is not limited to STEM.

The book was written to help the user learn the G programming syntax and begin developing $G$ programs quickly and easily. Although familiarity with programming concepts could help learning $G$, the book assumes the user has had no previous exposure to any programming languages. Therefore, to avoid confusion, no pseudocode or syntax comparisons are made with text-based programming languages. All examples in this book are working graphical examples and have been tested thoroughly. Chapter 1 is an introductory tutorial providing a reference for beginners and seasoned programmers alike. Subsequent chapters provide more details on the $G$ syntax building up to the development of parallel programs that run on multicore platforms.

This book is not an introduction to programming, style guide, debugging or to development environments. It is strictly a concise G syntax. Additionally, the user must have access to National Instruments LabVIEW and be familiar with LabVIEW basics. Nonetheless, the user should be able to read along to learn and understand the benefits of $G$ programming.

As one of the original LabVIEW development team members, developing G programs has been a pleasant and productive experience. It is the author's sincere hope that the user finds G programming and interesting endeavor as well.

Lalo Perez, Ph.D.

## About the Author

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Dr. Eduardo "Lalo" Perez is one of the original LabVIEW development team members responsible for the design, deployment and optimization of the Digital Signal Processing and Data Analysis Libraries still being used today.

Dr. Perez has nearly 30 years of engineering programming experience and nearly 20 years designing and implementing digital signal processing software architectures for the deployment of multimedia, communications and biomedical real-time applications. He has extensive experience in large enterprises -where he successfully deployed global multimedia networks and services for AT\&T and Ernst \& Young -as well as startups where he forged strategic alliances with Intel, Microsoft, Samsung and Texas Instruments to accelerate adoption of audio-visual services over IP. Dr. Perez' other accomplishments include: member of the first ever live video webcast team over ISDN in 1994, first commercial DSL live IP broadcast in 1999, provided nearly 3 years of webcasting services for Broadcast.com(now Yahoo! Broadcasting Services)with $100 \%$ success rate, team member at SBC Communications that launched SBC Internet Services and DSL services and provided guidance for deployment of early Internet multimedia communities.

Dr. Perez holds a variety of patents on high quality video encoding, compressive data acquisition, multirate media processing, remote computing and streaming delivery mechanisms.

A native from Mexico, he immigrated to the U.S. at the age of 18 to pursue higher education. He received his B.S., M.S., and Ph.D. in Electrical and Computer Engineering in the areas of Telecommunications, Image Processing, and Real-Time Digital Imaging Systems, respectively, all from the University of Texas at Austin.

Dr. Perez was a member of the 1976 Mexican Olympic Swimming team.

## Chapter 1 Introduction to G <br> Programming

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s.org/licenses/by-sa/4.0/).

G is a high level, data-flow graphical programming language designed to develop applications that are

- Interactive
- Execute in Parallel
- Multicore

The program is a block diagram edited in the Block Diagram programming window.


Figure 1.1 G Block Diagram
The program input data and results are manipulated and displayed in the Front Panel window.


Figure 1.2 G User Interface

### 1.1 Hello Graphical World

The first program is to display the text "Hello graphical interactive parallel multicore world" in the Front Panel window.

Right click on the Block Diagram window and select String Constant from the Functions » Programming » String menu.

Drag and drop the String Constant onto the Block Diagram window as show in the following Figure 1.3.


Figure 1.3 String Constant
Type in "Hello graphical interactive parallel multicore world." in the String Constant.


Figure 1.4 "Hello...world" String Constant
Right click in the Front Panel window and select a String Indicator from the Controls »Modern » String \& Path menu.


Figure 1.5 Select String Indicator
Drop it into the Front Panel window.


Figure 1.6 String Indicator
Return to the programming window. Notice the string terminal corresponding to thestring indicator in the Front Panel window. As you approach the string constant from the right, the wiring terminal is highlighted and the pointer turns to wire spooler.


Figure 1.7 Wiring the G Diagram
Click the "Hello graphical interactive parallel multicore world" terminal and then click on the String Indicator triangular terminal to wire the terminals.


Figure 1.8 Wired G Block Diagram

Save your program as Hello, World.vi. Return to the Front Panel window. Click the run button ([U+27AF]). You have successfully completed and executed your first G program.

## String

Hello Jraphical interactive
parallel multicore world.
Figure 1.9 Hello, World G Program Executed

### 1.2 Arithmetic Expressions

The next program converts degrees from Fahrenheit to Celsius using the formula

$$
C=\frac{5}{9}(F-32)
$$

In the Block Diagram window, select the subtract, multiply and divide from the Functions » Mathematics » Numeric menu


Figure 1.10 Numeric Operations
Wire the subtract, multiply and divide functions as shown in Figure 3.11.


Figure 1.11 Subtract, Multiply and Divide
Right click on the upper left terminal of the subtract function and select Create » Control from the pop-up menu.


Figure 1.12 Create Control
Re-labelx as Fahrenheit and wire the terminal as shown in Fahrenheit Input Control.


Figure 1.13 Fahrenheit Input Control
Right click on the lower left terminal of the subtract function and select Create »Constant and type 32.0.


Figure 1.14 Fahrenheit Numeric Constant
Repeat the process to generate numeric constants for the multiply and divide function with $\mathbf{5 . 0}$ and 9.0 respectively.


Figure 1.15 Fahrenheit Numeric Constants
To complete the program, right click on the right terminal of the divide function and select Create »Indicator. Re-label $\mathbf{x / y}$ as Celsius. The fnal diagram is shown in Fahrenheit to Celsius G Diagram


Figure 1.16 Fahrenheit to Celsius G Diagram
Switch to the Front Panel window to run the program. Save the program as Celsius.vi. Try various Fahrenheit values to see the corresponding Celsius values. You have successfully finished a Fahrenheit to Celsius calculator.

| Fahrenheit | Celsius |
| :--- | :--- |
| $\frac{1}{5}$ | 100 |

Figure 1.17 Fahrenheit to Celsius calculator

### 1.3 Functions

 s.org/licenses/by-sa/4.0/).Click on empty space and drag to select the entire diagram.


Figure 1.18 Select G Block Diagram
The selected diagram is highlighted as shown in Selected G Block Diagram


Figure 1.19 Selected G Block Diagram
From the Edit menu select Create SubVI to create a G function. The resulting diagram is shown in Creating a Function.

| Edit | Yiew Project |
| :---: | :---: |
| Undo Window Size |  |
| Redo |  |
| Cut |  |
| Copy |  |
| Paste |  |
| シ |  |
|  | eate subvi |

Figure 1.20 Creating a Function
From the File menu select Save All and save the Untitled function as Fahrenheit to Celsius.vi.


Figure 1.21 Diagram with Function
Open the Fahrenheit to Celsius.vi by double clicking on the icon. Right click on the icon editor (upper right corner) and select Edit Icon...


Figure 1.22 Edit Icon
This pops-up the Icon Editor. Edit the function's icon.


Figure 1.23 Icon Editor
After editing the icon, the function's icon is shown in the upper right corner of the Front Panel window. Save the function, plug in various input values and run the function. Save the function.


Figure 1.24 Edited Icon
Close theFahrenheit to Celsius function and return to the Celsius Block Diagram windows. The Celsius diagram reflects the updated Fahrenheit to Celsius icon


Figure 1.25 Function Calling

### 1.4 Case Selection

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This program determines if a year is a leap year or not. A leap year is divisible by 4 but not by 100 , except when it is divisible by 400 . A number $x$ is divisible by a number $y$ if the remainder of $x / y$ is identical to zero, i.e. $\operatorname{Rem}(x / y\}=0$ is true therefore

Leap Year $=\{\operatorname{Rem}($ Year/4 $)=0$ And Not $($ Rem $($ Year/100 $)=0)\}$ Or Rem $($ Year/400 $)=0$ (3.1)
where And, Or and Not are Boolean operators.
For example:
1900 is not a leap year because it is divisible by 100
1970 is not a leap year because it is not divisible by 4

1980 is a leap year because it is divisible by 4 but not by 100
2000 is a leap year because it is divisible by 400
Start a new G program and right click on the Block Diagram window. Go to the Functions » Programming » Numeric menu in the Block Diagram window.


Figure 1.26 Quotient \& Remainder Function
Select three copies of the Quotient \& Remainder function and three numeric constants. Type in 4, 100 and 400 for the numeric constants and wire these constants to the lower input terminal (corresponding to the dividend) of the Quotient \& Remainder function.


Figure 1.27 Leap Year Numeric Constants
From the Functions » Programming » Comparison menu, select 2 copies of the Equal to Zero function and one copy of the Not Equal to Zero function.


Figure 1.28 Comparison Functions
Organize the comparison operations as show in the diagram.


Figure 1.29 Diagram

From the Functions » Programming »Boolean menu select the AND and OR operators


Figure 1.30 Boolean Operators
Place the Boolean operators as shown in Q\&R, Comparison \& Boolean Functions.

 vi

$\Rightarrow$
Figure 1.31 Q\&R, Comparison \& Boolean Functions
From the Functions » Programming »Structures menu, click on the Case Structure.


Figure 1.32 Case Structure
Click and drag on the Block Diagram window to create the Case Structure.


Figure 1.33 Creating a Case Structure
The True diagra $m$ option is indicated at the top of the case structure.


Figure 1.34 Created Case Structure
Drop a string constant and type "Is a Leap Year".


Figure 1.35 True Case Editing
Click on the down arrowhead next to the True label and select the False option .


Figure 1.36 Selecting the False Case
Drop another string constant and type "Is not a Leap Year".


Figure 1.37 False Case Editing
Go to the Front Panel window and place a numeric input and an output string. Relabel the numeric input to Year and the output string to Message.


Figure 1.38 Leap Year GUI
Right click on Year and select Representation » I32 from the numeric pop-up menu.


Figure 1.39 32-Bit Integer Numeric
Arrange the Year and Message terminals in the Block Diagram window as shown in the figure.


Figure 1.40 Unwired Leap Year Diagram
Wire the OR operator is to the "7" in the case structure and the string constant "Is not a Leap Year" is wired to Message.


Figure 1.41 Leap Year False Case
Select the True option and Wire the "Is a Leap Year" string constant to the output terminal of the Case Structure.


Figure 1.42 Leap Year True Case
Save the program as Leap Year.vi, enterYear values and run the program to determine whether the value of Year is that of a leap year or not.


Figure 1.43 Leap Year Program

### 1.5 Arrays

Right click on the Front Panel window and selectArray from the Controls » Modern » Arrays, Matrix \& Cluster menu, and drop an array onto the Front Panel window. The array structure consists of an index or element offset (left portion of the structure) and the array elements (right portion of the structure). When the array structure is placed on the Front Panel window, the data type of the array is undefned as indicated by the grayed out portion of the array.


Figure 1.44 Arrays
To define the array data type, drag and drop a data type onto the array structure. For instance, to create an input array of numbers, place Numeric Control into the array structure.


Figure 1.45 Creating a Numeric Array
At this point, the numeric array is an Empty or Null array because no elements of the array have been defned. This is indicated by the grayed out numeric control within the array structure.


Figure 1.46 Empty Numeric Array
Define elements of an input array by selecting the offset and entering its value. For instance, at ofset 4, enter the value 0.0. This defines Numeric Input Array as $\{0,0,0$, $0,0\}$.


Figure 1.47 Defining Numeric Array Elements
An output array is created similarly to an input array with the exception that an output data type needs to be dropped into the array structure.


Figure 1.48 Creating Output Numeric Arrays

### 1.6 For Loop

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This program converts an array of Fahrenheit values to Celsius. Create numeric input and output arrays and label them Fahrenheit and Celsius respectively. In the Fahrenheit array enter the values $0,20,40,60,80,100,120,140,160,180$ and 200 at ofsets 0 through 10 as shown in Numeric Input and Output Arrays.


Figure 1.49 Numeric Input and Output Arrays
Right click in the Block Diagram window, navigate to Programming » Structures and click on For Loop.


Figure 1.50 For Loop Structure
Click and drag to create the For Loop as shown in Creating For Loops and For Loop.


Figure 1.51 Creating For Loops


Figure 1.52 For Loop
Right click inside the For Loop and select Select a VI... from the pop-up menu. Find the Fahrenheit to Celsius.vi and clickOK. Drop the function inside the For Loop.


Figure 1.53 Function in Diagram

To complete the program, wire the Fahrenheit input array to the input terminal of the Fahrenheit
to Celsius function and wire the output terminal of the Fahrenheit to Celsius function to the Celsius output array.


Figure 1.54 Wired Function in Diagram
This program uses the For Loop to select each element in the Fahrenheit input array, converts that value to Celsius and saves the results in the Celsius output array. Save the program as Fahrenheit to Celsius For Loop.vi and run the program.


Figure 1.55 Fahrenheit to Celsius Arrays
The Celsius output array contains: Celsius $\{-17.7778,-6.6667,4.44444,15.5556$, $26.6667,37.7778,48.8889,60,71.1111,82.2222,93.3333\}$

### 1.7 While Loop

The next program will generate Fahrenheit values and convert them to Celsius until a condition is met to stop the iterations in a While Loop. In the Block Diagram window, select the While Loop structure by clicking on it from the Functions » Programming » Structures menu.

Click and drag to create the While Loop structure.


Figure 1.56 While Loop Structure


Figure 1.57 Creating a While Loop


Figure 1.58 While Loop
In the Front Panel window, create two numeric output arrays. Label them Fahrenheit and Celsius.


Figure 1.59 Numeric Output Arrays
Re-arrange the diagram as in While Loop Diagram .


Figure 1.60 While Loop Diagram
From the Functions menu, select Multiply function and a couple of numeric constants. Type in $\mathbf{2 0 . 0}$ and $\mathbf{3 0 0 . 0}$ for the numeric constants. Select the Fahrenheit to Celsius.vi and drop it inside the While Loop. Re-arrange the diagram to look like Generating Fahrenheit Values


Figure 1.61 Generating Fahrenheit Values
From the Functions » Programming » Comparison menu select the Greater or Equal operator.


Figure 1.62 Greater or Equal Function Description
Wire the While Loop components as shown in Generating Fahrenheit Values \& Stop Condition.


Figure 1.63 Generating Fahrenheit Values \& Stop Condition
Wire the output of the Multiply operation to theFahrenheit and the output of the Fahrenheit to Celsius function to the Celsius numeric output arrays. The connections between the While Loop and the Fahrenheit andCelsius arrays are broken (see Broken Wires).


Figure 1.64 Broken Wires
To repair the broken connections, roll over the mouse pointer to the Loop Tunnel.


Figure 1.65 Loop Tunnel
Right click on the Loop Tunnel and select Enable Indexing from the pop-up menu.
Figure 1.66 [/topic/body/fig/title/title \{"- topic/title "\}) Enable Loop Indexing (title]
This enables values to accumulate and store the results into an array. Repeat for the Celsius array.


Figure 1.67 Broken Wire Repaired
Each iteration of the While Loop in this program generates an $\mathbf{i} \times \mathbf{2 0}$ Fahrenheit value and converts it to Celsius. The While Loop stops iterating when the generated Fahrenheit value is greater than or equal to 300. The resulting arrays are stored in the Fahrenheit and Celsius numeric output arrays.

Save the program as Fahrenheit to Celsius While Loop.vi and run it. The program generates the following results:


Figure 1.68 Fahrenheit to Celsius While Loop
Fahrenheit $\{0,20,40,60,80,100,120,140,160,180,200,240,260,280,300\}$
Celsius $\{-17.7778,-6.6667,4.44444,15.5556,26.6667,37.7778,48.8889,60,71.1111$, 82.2222, 93.3333, 104.444, 115.556, 126.667, 137.778, 148.889\}


Figure 1.69 Fahrenheit and Celsius Arrays

### 1.8 Graphs

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s.org/licenses/by-sa/4.0/).

Using the previous $G$ program example, we will now visualize the results by adding a graph to the Front Panel windows. Right click on the Front Panel window. Select XY Graph from the Controls » Modern » Graph menu.


Figure 1.70 XY Graph Selection
Drop the XY Graph in the Front Panel window. Double click on the x and y axis labels and renameTime to Fahrenheit and Amplitude to Celsius.


Figure 1.71 XY Graph in Front Panel window
The Block Diagram window contains theXY Graph terminal.


Figure 1.72 XY Graph Terminal in Diagram
Select Bundle from the Functions » Programming » Cluster, Class \& Variant menu


Figure 1.73 Bundle Operator
Drop it on the diagram as shown in Bundle for XY Graph.


Figure 1.74 Bundle for XY Graph
Wire the Fahrenheit and Celsius results to the input Bundle terminals and the output Bundle terminal to the XY Graph.

Save the program and run it. The resulting graph is shown in the fgure below.


Figure 1.75 Wired XY Graph


Figure 1.76 XY Graph Result

### 1.9 Interactivity

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This $G$ program shows how $G$ allows programmers to develop interactive programs. Create the following $G$ program and wire it as shown in the figure below.


Figure 1.77 Creating Interactive Programs
In the Front Panel window, from the Functions » Modern » Numeric select the vertical pointer slide. From the Functions » Modern » Graph select Waveform Chart.


Figure 1.78 Vertical Pointer Slide and Waveform Chart
Re-label the vertical pointer slide as Amplitude and the waveform chart as Sine Wave. Re-arrange to GUI to look like the figure below.


Figure 1.79 Slide \& Waveform Chart in Front Panel window
Right click on Sine Wave and selectProperties from the pop-up menu.


Figure 1.80 Selecting Chart Properties
Select the Scales tab and change Maximum to 1023. Sine Wave will display 1024 samples. Click on the down arrow located to the right of Time (XAxis) and select Amplitude (YAxis).


Figure 1.81 X-Axis Maximum


Figure 1.82 Selecting Y-Axis
De-select Autoscale and change the Minimum and Maximum values to $\mathbf{- 1 0}$ and $\mathbf{1 0}$. Click OK.

De-Selecting Autoscale

| Appearance | Dsplay Format | Plots | Scales | Documentat |
| :---: | :---: | :---: | :---: | :---: |
| Amplitude ( $\mathrm{Y}-\mathrm{A} \times 15$ ) |  |  |  | , |
| Name Amplizude |  |  |  | Minimum <br> Maximum |
| Show scale label <br> show scale |  | Autoscale |  |  |
|  |  | -10 |  |  |
| $\square$ Log |  | 10 |  |  |

In the Block Diagram window, re-arrange the Amplitude and Sine Wave terminals and finish the program as shown in Interactive Sine Wave Diagram.


Figure 1.83 Interactive Sine Wave Diagram
Scroll the mouse pointer over the Loop Control...


Figure 1.84 Loop Condition
And right click on theLoop Control and from the pop-up menu selectCreate Control. A stop terminal is created...


Figure 1.85 Create Loop Control


Figure 1.86 Interactive G Program
With the correspondingstop Boolean input control. Save the G program as Interactivity.vi.


Figure 1.87 Interactive Program
Run the G program.


Figure 1.88 Interactive Program
While the program is running, change the Amplitude and watch the graph update to refect the interactive changes.


Figure 1.89 Interactive Program
To end the G program, simply click on the stop button. Congratulations. You have successfully completed and executed your first interactive G program.


Figure 1.90 Interactive Program

### 1.10 Parallel Programming

Save a copy of Interactivity.vi as Parallel Programming.vi. Select the while loop as shown in Select Diagram for Parallel Programming.


Figure 1.91 Select Diagram for Parallel Programming
From the menu select Edit »Copy.


Figure 1.92 Copy Selected Diagram
Create a copy of the while loop and its contents by selecting Edit » Paste. Organize the diagram as shown in the figure below.


Figure 1.93 Paste Diagram
Go the Front Panel window and organize the input and output controls as shown in the figure below.


Figure 1.94 Parallel G Program
Congratulations!!! You have just completed your frst parallel interactive program using G. Save the program, run it and interact with it. To end this program click on stop and stop 2.


Figure 1.95 Parallel Interactive G Program

### 1.11 Multicore Programming

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s.org/licenses/by-sa/4.0/).

Save a copy of Parallel Programming.vi as Multicore Programming.vi. If you have a multicore computer, CONGRATULATIONS!!! You have just completed your first multicore G program.


Figure 1.96 Interactive Multicore G Program

### 1.12 Polymorphism

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s.org/licenses/by-sa/4.0/).

This program shows the polymorphic properties of G. Create the G program shown below. Notice that the Subtract and Multiply operations allow arrays to be wired in the $G$ program.


Figure 1.97 Polymorphic G Diagram

## Chapter 2 Data Types

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| Data Type | Block Diagram Terminal |  | Interactive User |  | nfterfacents |
| :---: | :---: | :---: | :---: | :---: | :---: |
|  | Input | Output | Input | Outp | put |
| Extended | $\begin{gathered} 8 \\ \hline 8.23 \mathrm{E} \\ \hline \end{gathered}$ |  | $1.2345$ |  | 80-bit floating pointnumeric |
| Double |  |  | 1.2345 |  | 64 -bit floating pointnumeric |
| Single | $\begin{array}{\|c\|} \hline 8.230 \\ 560 \\ \hline \end{array}$ |  | $1.2345$ |  | 32-bit floating pointnumeric |
| ComplexExtended | $\begin{array}{\|c\|} \hline \text { 6. } 1.23 \mathrm{c} \\ \hline \text { c87 } \\ \hline \end{array}$ | $\begin{array}{\|c\|c\|} \hline 15 & 1.2+3.4 i \\ \hline \end{array}$ | $1.2+3.4 i$ |  | 160 -bit floating pointnumeric |
| ComplexDouble |  | $1.2+3.4 i$ | $1.2+3.4 i$ |  | 128-bit floating pointnumeric |

Figure 2.1

| ComplexSingle |  | $1.2+3.41$ | 64-bit floating pointnumeric |
| :---: | :---: | :---: | :---: |
| Integer 64 |  | $-12345$ | 64-bit signed integernumeric |
| Integer 32 |  | $-12345$ | 32-bit signed integernumeric |
| Integer 16 |  | $-12345$ | 16-bit signed integernumeric |
| Integer 8 |  | $-123$ | 8-bit signed integernumeric |
| UnsignedInteger 64 |  | $12345$ | 64-bt unsigned integer numeric |
| UnsignedInteger 32 |  | $12345$ | 32-bit unsigned integer numeric |
| Unsignedinteger 16 |  | $12345$ | 16-bit unsigned integer numeric |
| UnsignedInteger 8 |  | $123$ | 8-bit unsigned integer numeric |
| Fixed Point |  | $1.2345$ | Mantissa. fractional fixed point numeric representation |

Figure 2.2


Figure 2.3

## Chapter 3 Operators

### 3.1 Numeric

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$\|$ Programming
$L_{\text {Numeric }}$


| (1) |  | $22 \%$ |  | 3 |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Round Towar... | Round Towar... | Scale By Pow... | Complex | Square Root | Square | Negate |
| $i /$ | $\sqrt{0}$ | $\begin{array}{\|c\|} \hline m x+b \\ 2+v \\ \hline \end{array}$ | 123 | 4 Enum | Ring | 蛤 |
| Reciprocal | Sign | Scaling | Numeric Cons... | Enum Constant | Riny Constant | Random Num... |
| [EXPR] | $+\infty$ | - | ¢ |  |  |  |
| Expression $\mathrm{N} . .$. | +Inf | -Inf | Machine Epsilon | Math Constants |  |  |

Figure 3.1 Numeric Operators
$\|$ Programming
$L_{\text {Numeric }}$
$L_{\text {Complex }}$


Figure 3.2 Complex Numeric Operations Figure : Numeric Conversion Operators
$\|$ Programming
$L_{\text {Numeric }}$
$\mathrm{L}_{\text {Data }}$ Manipulation


Figure 3.3 Numeric Data Manipulation Operators
\｜Programming
$L_{\text {Numeric }}$
$L_{\text {Conversion }}$

| EXT | ［DEL | ［SEL | IFXP | 164 | ［132） | 516 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| To Extended ．．． | To Double Fr．．． | To Single Pre．．． | To Fixed－Point | To Quad Inte．．． | To Long Integer | To Word Inte．．． |
| 18） | （064） | ［032） | 516 | （08） | EXT | CDB |
| To Byte Integer | To Unsigned ．．． | To Unsigned ．．． | To Unsigned ．．． | To Unsigned ．．． | To Extended ．．． | To Double Pr．．． |
| CSC |  | ［ $\cdots$ | ［1：0 | ［\＃－（1） | ［［08］ | ［108］ |
| To Single Pre．．． | Number To 3．．． | Boolean Arra．．． | Boolean To（0．．． | To Time Stamp | String To Byt．．． | Byte Array T．．． |
| ［UNTIT | － |  |  |  |  |  |
| Convert Unit | Cast Unit Bases |  |  |  |  |  |

Figure 3．4 Numeric Conversion Operators

## 3．2 Boolean

－Programming $\mathrm{L}_{\text {Boolean }}$

| （A） | v＞ | \＃＊ | $\phi$ | 曰部 | （A） |
| :---: | :---: | :---: | :---: | :---: | :---: |
| And | Or | Exclusive or | Not | Compound Ar．．． | Not And |
| Vo | D＊ | $\Rightarrow$ | 7 V | 3 | ［\＃\＃$\cdots$ |
| Not Or | Not Exclusive．．． | Implies | And Array Ele．．． | Or Array Ele．．． | Num to Array |
| ［［－］I\＃ | ［1：0 | 围 | \％ |  |  |
| Array to Num | ＂Bool to（0，1）＂ | True Constant | False Constant |  |  |

Figure 3．5 Boolean Operators

## 3．3 Comparison

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s．org／licenses／by－sa／4．0／）．
$\|$ Programming
$L_{\text {Comparison }}$

| $\geqslant$ | $\geqslant>$ | $\geqslant>$ | $\leqslant>$ | $\geqslant$ | $\leqslant>$ | 0 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Equal？ | Not Equa？ | Greater？ | Less？ | Greater Or E．．． | Less Or Equal？ | Equal To 0？ |
| $\geqslant$ | $\geqslant 0$ | $\leqslant 0$ | $30$ | si） |  |  |
| Not Equal To 0？ | Greater Thaา 0？ | Less Than 0？ | Greater Or E．．． | Less Or Equal．．． | Select | Max \＆Min |
| $\begin{array}{ll} \diamond & \rightarrow \\ \Leftrightarrow & ? \end{array}$ | $\theta>$ | $y\rangle$ | $\ddot{B}$ | $\hat{i}\rangle$ | $\stackrel{\phi}{\hat{o}}\rangle$ |  |
| In Range and．．． | Not A Numbe．．． | Empty Array？ | Empty Stringi＇．． | Decimal Digit？ | Hex Digit？ | Octal Digit？ |
|  | $\geqslant\rangle$ | $\hat{2} \geqslant$ | $\stackrel{?}{=}$ |  |  |  |
| Printable？ | White Space？ | Lexical Class | Comparison |  |  |  |

Figure 3．6 Comparison Operators


Figure 3.7 String Operators
| $\downarrow$ Programming
$L_{\text {Sxing }}$
$\mathrm{L}_{\text {Stringi/Number Conversion }}$


Figure 3.8 String/Number Operators

### 3.4 Math

### 3.4.1 Math Constants

$\|$ Programming
$\mathrm{L}_{\text {Numeric }}$
$L_{\text {Math \& Scientific Constants }}$

| $\pi$ | $2 \pi$ | T/2 | 1/TI | \|nT] | e |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Pi | 2*Pi | $\mathrm{Pi} / 2$ | 1/Pi | $\ln (\mathrm{Pi})$ | e |
| 1/e | 109,0 | Into | $\underline{4} 2$ | h | e |
| 1/e | $\log 10(\mathrm{e})$ | $\ln (10)$ | $\ln (2)$ | Planck's Cons... | Elementary C... |
| c | G | Na | R | R |  |

Speed Of Lig... Gravitational ... Avogadro Co... Rydberg Con... Molar Gas Co...
Figure 3.9 Mathematical Constants

### 3.4.2 Trigonometric Functions

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- Mathematics
$\mathrm{L}_{\text {Elementary \& Special Functions }}$
$\mathrm{L}_{\text {Trigonometric Functions }}$


Figure 3.10 Trigonometric Functions

### 3.4.3 Exponential and Logarithmic Functions

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- Mathematics
$L_{\text {Elementary \& Special Functions }}$ $L_{\text {Exponential Functions }}$


Figure 3.11 Exponential and Logarithmic Functions

### 3.4.4 Hyperbolic Functions

- Mathematics
$L_{\text {Elementary \& Special Functions }}$
$L_{\text {Hyperbolic Functions }}$


Figure 3.12 Hyperbolic Functions

## Chapter 4 Arrays and Clusters

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To create an array in G, right click on the Front Panel window and select Array from the Controls » Modern » Arrays, Matrix \& Cluster menu, and drop the array structure onto the Front Panel window to create an array.


Figure 4.1 Array Structure
The array structure consists of an index or element offset (highlighted left portion of the array structure) and the array elements (right portion of the structure). When the array structure is placed on the Front Panel window, the data type of the array is undefined as indicated by the grayed out portion of the array.


Figure 4.2 Index and Elements of an Array
To define the array data type, drag and drop any data type, such as numeric, Boolean, string or cluster structure, onto the elements portion of the array structure.


Figure 4.3 Creating Arrays
At this point, the newly defined array is anEmpty orNullArray because no elements of the array have been defined. This is indicated by the grayed out data type within theelements array structure.


Figure 4.4 Empty Arrays
To define elements of an input array, select the element's index and enter the appropriate value. Figure 6.5 defines a numeric array with one element at index 0 .


Figure 4.5 Defining Array Elements
G arrays are zero-based. The last element index of an $\mathbf{N}$ element array is $\mathbf{N} 1$. Last Array Element and Undefined Nth Element are those of a 10 element array.


Figure 4.6 Last Array Element


Figure 4.7 Undefined Nth Element
An output array is created similarly to an input array with the exception that an output data type needs to be dropped into the array structure.


Figure 4.8 Input and Output Arrays

### 4.1 Multidimensional Arrays

To create multidimensional arrays, click on the array's index and select Add
Dimension from the menu. Multidimensional Array shows a 2-dimensional array.


Figure 4.9 Creating Multidimensional Arrays


Figure 4.10 Multidimensional Array

### 4.2 Array Operators

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s.org/licenses/by-sa/4.0/).
$\|$ Programming
$L_{\text {Array }}$


Figure 4.11 Array Operators

### 4.3 Clusters

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s.org/licenses/by-sa/4.0/).

Clusters allow users to create compound data types by aggregating various and different data types into a single unit.


Figure 4.12 Empty Cluster
Select the various data types and drag them onto the cluster structure. Figure Figure 4.13shows an Error Cluster consisting of a Boolean Error, a numeric ID and a string Message data types.


Figure 4.13 Cluster Example

### 4.4 Cluster Operators



Figure 4.14 Cluster Operators

## Chapter 5 Data Flow Control

### 5.1 Case Structure

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s.org/licenses/by-sa/4.0/).

The case structure allows data to flow based on a integer, Boolean or string matching condition. The case executed is selected based on the data wired to theCase Selector.


Figure 5.1 Case Structure

### 5.1.1 Boolean Selection

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In the Front Panel window, select a Boolean control and an output string.


Figure 5.2 Case Selection User Interface
Arrange the diagram to look as in Case Selection G Diagram.


Figure 5.3 Case Selection G Diagram
In the True case, add a string constant containing True Case.


To select the False case, click on the selector label down arrow and select False from the pop-up menu. You can also cycle through the cases by clicking the next (right) or previous (left) arrows.

Selecting False Case
Boolean


In the False case, add a string constant containing False Case.


Figure 5.5 False Case Diagram
Wire the string constant in the case structure to the output string terminal.


Figure 5.6 Wiring Case Structures
Select theTrue case and wire the string constant to the case structure tunnel.
Complete the diagram as shown in Completed Case Diagram.


Figure 5.7 Completed Case Diagram
It is important to note that all instances in a case structure must be wired to enable data to flow from thecase structure.

In the Front Panel window, toggle the Boolean input control and run the program.


Figure 5.8 False Selection


Figure 5.9 True Selection

### 5.1.2 Multicase Selection

Select an Integer 32 numeric input and an Integer 32 numeric output and label them Selector and Case respectively.


Figure 5.10 Multicase GUI
In the Block Diagram window, create a case structure, select the False case and arrange the terminals as shown in Multicase.

Selector


Case


Figure 5.11 Multicase
Wire the Selector numeric control to the case selector on the case structure. The selector label reflects the diagram update.


Figure 5.12 Multicase Selector
In the $\mathbf{0}$, Default case, add a numeric constant and leave its value as 0 .


Figure 5.13 Default Case
Using the selector label, select case 1. Add a numeric constant, enter 1 and wire it to the case tunnel. The resulting diagram is shown in Case 1.


Figure 5.14 Case 1
Right click anywhere in the case structure and selectAdd Case After from the pop-up menu.


Figure 5.15 Adding Cases
Case 2 is added after case 1 . Add a numeric constant, enter $\mathbf{2}$ and wire it to the case structure tunnel.


Figure 5.16 Case 2
Multicase Selection Program shows the results of running this simple case selection programs for Selector set to 0, 1, 2 and 3 respectively.


Figure 5.17 Multicase Selection Program

### 5.2 For Loop

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The For Loop structure repeatedly executes the diagram within the structure. The Loop Count specifies the number of times the loop contents must be executed and the Loop Iteration indicates which iteration is currently being executed.


Figure 5.18 For Loop Structure
The Loop Count and Loop Iteration are of Integer 32 data types. If the Loop Count is set to $\mathbf{N}$, then the Loop Iteration value range is from $\mathbf{0}$ to $\mathbf{N} 1$. This is illustrated in Loop Count and Final Loop Iteration.


Figure 5.19 Loop Count


Figure 5.20 Final Loop Iteration

### 5.2.1 Shift Registers

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Shift Registers allow the preservation of intermediate results between sequences of iterations.


Figure 5.21 Shift Registers


Figure 5.22 Shift Registers
To add a Shift Register, right click on the For Loop structure and select Add Shift Register from the pop-up menu.


Figure 5.23 Adding Shift Registers
To add elements to the shift register, right click on the shift register and select Add Element from the pop-up menu.


Figure 5.24 Adding Shift Register Elements


Figure 5.25 Adding Shift Register Elements
To illustrate the use of the shift registers, the following example computes the Fibonacci number Fib(n).

$$
0, \quad n=0
$$

$\operatorname{Fib}(n)=\{$
1,
$n=1$
$\operatorname{Fib}(n-1)+\operatorname{Fib}(n-2), \quad n>1$

In the Front Panel window, select an integer 32 numeric input and output controls and labeled them $\mathbf{n}$ and $\mathbf{F i b}(\mathbf{n})$ respectively. Arrange the diagram as shown in Shift Register Example.


Figure 5.27 Shift Register Example
Add a $\mathbf{0}$ and $\mathbf{1}$ numeric constants to initialize the elements of the shift register and wire them to the $\mathbf{i}-\mathbf{1}$ and $\mathbf{i}-\mathbf{2}$ elements respectively. Add the add operator in the for loop and complete the program wiring as shown in Fibonacci G Program.


Figure 5.28 Fibonacci G Program
For $\mathbf{n}=0$, the for loop iterates 0 times and passes 0 to $\operatorname{Fib}(\mathbf{n})$, therefore Fib(0) 0 . For n 1 , the for loop the values ini-1 and $\mathbf{i}-\mathbf{2}$ shift register elements are added ( $0+1$ ) and saved in the i shift register element (1). Since the loop iterates once only, the resulting value is passed toFib(n), therefore $\mathrm{Fib}(1) 1$. For $\mathrm{n}=2$, the first iteration produces the value of 1. Prior to the next and final iteration, the values are shifted in the register as follows:

The value in the $\mathbf{i} \mathbf{- 2}$ shift register element is discarded
The value in the $\mathbf{i} \mathbf{- 1}$ shift register element is shifted to the $\mathbf{i} \mathbf{- 2}$ shift register element The value in the $\mathbf{i}$ shift register element is shifted to thei-1 shift register element To start the $2^{\text {nd }}$ and final iteration, thei- $\mathbf{1}$ shift register element contains 1 and the $\mathbf{i}-\mathbf{2}$ shift register element contains 0 . These are added to produce 1 , which is passed to $\mathbf{F i b}(\mathbf{n})$ and, therefore, $\mathrm{Fib}(2) 1$. This process is repeated for values of $\mathbf{n}>2$.

Save this program as Fibonacci.vi. Figure 7.29 shows the result of Fib(8).


Figure $5.29 \mathrm{Fib}(8)=21$

### 5.2.2 Auto-Indexing

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Auto-indexing allows input array elements to be operated on and output array elements to be aggregated automatically in a for loop. It is not required to wire the Loop Counter. The for loop automatically reduces the array dimensionality by one.


Figure 5.30 For Loop Auto-Indexing

### 5.2.3 Disabling Auto-Indexing

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s.org/licenses/by-sa/4.0/).

It is sometimes necessary to disable auto-indexing. In this example, the For Loop is used to scan the elements of the array taking advantage of the auto-indexing feature. However, the result is a single number. Wiring the result through the For Loop with auto-indexing enabled results in a broken data type wire.


Figure 5.31 Broken Auto-Indexing
To disable auto-indexing, right click on the target Auto-Indexed Tunnel and select Disable Indexing from the pop-up menu.


Figure 5.32 Disabling Auto-Indexing
The final diagram with the Auto-Indexed Tunnel disabled is shown in Disabled AutoIndexing.


Figure 5.33 Disabled Auto-Indexing

### 5.3 While Loop

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s.org/licenses/by-sa/4.0/).

The While Loop conditionally iterates executing the statements within the structure. The Loop Condition establishes whether the loop iterates or terminates. TheLoop Iteration is a zero-based iteration execution reference similar to the For Loop.


Figure 5.34 While Loop Structure

### 5.3.1 Loop Condition

### 5.3.1.1 Stop if True

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s.org/licenses/by-sa/4.0/).

The default loop condition is to continue if the Boolean condition is False (or stop if True). The while loop in the following Figure 5.35 will iterate while Iterations is less than Loop Iteration is False or, equivalently, will stop iterating whenIterations is less than the value in Loop Iteration.


Figure 5.35 Stop If True

### 5.3.1.2 Continue if True

## c) © ©

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At times it is more convenient to let the while loop iterate while the condition is True. To change the loop condition, right click on the loop condition icon and select Continue if True from the pop-up menu.


Figure 5.36 Changing Loop Condition
Continue If True shows the Loop Condition set to Continue if True.


Figure 5.37 Continue If True

### 5.3.2 Shift Registers

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s.org/licenses/by-sa/4.0/).

Programmatically, while loop shift registers are identical to for loop shift registers. Refer to Section Shift Registers for the discussion. However, an example is provided to illustrate the use of shift registers in while loops.


Figure 5.38 While Loop Shift Registers
In the following example, Euler's number e is computed to the specified accuracy using the infinite series

$$
\mathrm{e}=\frac{-b \pm \sqrt{b^{2}-4 a c}}{2 a}=\sum_{n=0}^{n=\infty} \frac{1}{n!}=1++\sum_{n=0}^{n=\infty} \frac{1}{n!}=1+\frac{1}{1!}+\frac{1}{2!}+\frac{1}{3!}+\cdots=2.7182818284 .
$$

Notice that two shift registers keep track of the factorial and the sum. Also notice the dot in the multiplication. This is because the loop iteration is an integer 32 data type and the input from one of the shift registers is double precision numeric. The dot represents that the integer 32 data type has been coerced into a double precision number.


Figure 5.39 Computing e
Save the program as e.vi. The result of running this program is shown in Computed e to 5 Digits.

| Accuracy <br> (5) <br> 5 |  | $1 \mathrm{E}-5$ |
| :--- | :--- | :--- |
|  | 2.71328 |  |

Figure 5.40 Computed e to 5 Digits

### 5.3.3 Enabling Auto-Indexing

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By default, while loops are auto-indexed disabled. In order for while loops to process and generate arrays, the loop tunnel must be enabled to auto-indexed arrays.


Figure 5.41 Disabled Auto-Indexing
To enable auto-indexing, right click on the loop tunnel and select Enable Indexing from the pop-up menu.


Figure 5.42 Enabling Auto-Indexing
In this example the while loop appropriately generates a 1,000 element numeric array with random numbers.


Figure 5.43 Auto-Indexing Enabled

### 5.4 Sequence

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Although $G$ was designed to easily develop interactive, parallel programs, it is sometimes necessary to execute diagrams in sequential order. The sequence structure allows $G$ diagrams to execute sequentially.

The following examples time in milliseconds (ms) the execution of a G diagram. The sequence of events is get a start time stamp, execute the diagram, get stop time stamp and take the difference between the stop and start times to determine the execution time.


Figure 5.44 Sequence Structure

### 5.4.1 Flat Sequence

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Flat Sequences always execute left to right. A Flat Sequence structure starts with a single frame and allows a user to visualize the diagram sequences.


Figure 5.45 Sequence Frame
To add frames to a sequence, right click on the sequence structure and select either Add Frame After or Add Frame Before from the pop-up menu according to the program's needs.


Figure 5.46 Adding Sequence Frames
Add two more frames to the sequence structure to get a three frame sequence as shown in Three Frame Sequence.


Figure 5.47 Three Frame Sequence
From the Functions » Programming » Timing menu select Tick Count (ms) function.


Figure 5.48 Tick Count Function
Drop the Tick Count (ms) function in the frst (left most) frame of this sequence. Make a copy of the Tick Count function and place it on the third (right most) frame as shown in Start and Stop Tick Counts.


Figure 5.49 Start and Stop Tick Counts
Add a For Loop that iterates 5,000 times to the second frame. Add a subtract operator, an unsigned integer 32 output and complete the program as shown in Timing G Program. The execution of this program shows the time in milliseconds it took for the $2^{\text {nd }}$ sequential frame to execute.


Figure 5.50 Timing G Program

### 5.4.2 Stacked Sequence

A Stacked Sequence provides a more compact representation of program sequences. It is programmatically identical to the Flat Sequence with the exception that a Sequence Local enables data to flow to subsequent frames. Additionally, as frames are added, a Sequence Selector provides access to the desired frame (see Stacked Sequence).


Figure 5.51 Stacked Sequence
For this timing example, start with a Stacked Sequence and add 3 more frames. The sequence frames are labeled $0,1,2$ and 3 and will execute in that order.


Figure 5.52 Four Frame Stacked Sequence
Go to the first frame (frame 0) and add a Tick Count (ms) function. Right click on the sequence structure and select Add Sequence Local from the pop-up menu.


Figure 5.53 Adding Sequence Locals


Figure 5.54 Adding Sequence Locals
The Sequence Local is shown as an undefined tunnel. Wire the Tick Count (ms) function to the Sequence Local to define the tunnel data type and data flow. Data can now flow from frame 0 to the other frames as needed.


Figure 5.55 Sequence Local

## Figure 5.56 Sequence Local

Go to the next frame sequence (frame 1) and enter the program to be timed.


Figure 5.57 Frame to Time
Go to the third frame of the sequence (frame 2), add a Tick Count (ms) function, add another Sequence Local and wire the Tick Count (ms) to the new Sequence Local. The wired sequence frame is shown in Stop Time Stamp.


Figure 5.58 Stop Time Stamp
Go to the last frame (frame 3) and add aSubtract function. Wire the Sequence Locals from frame 2 and frame 0 to the Subtract function as shown in Stacked Timing G Program. To complete the diagram, wire the output of the Subtract function to the unsigned integer 32 output.


Figure 5.59 Stacked Timing G Program
It is important to note that the programs in Timing G Program and Stacked Timing G Program are programmatically identical.

## Chapter 6 Functions

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Any G program can become a function. Three operations must be done:

1. Edit connecting input and/or output terminals
2. Edit the icon (optional but recommended)
3. Save the G program

### 6.1 Connectors

Open the Fibonacci.vi for this example.
On the Front Panel window, right click on the icon located on the right upper corner of the window and select Show Connector.


Figure 6.1 Show Connector Pane
This brings up the connector pane as shown in Connector Pane.


Figure 6.2 Connector Pane
Right click on the connector pane and select Patterns. A menu with connector patterns is presented from which you can select the appropriate pattern. For this example select the pattern highlighted in Select Connector Pattern.


Figure 6.3 Select Connector Pattern

Click on the connector terminal followed by a click on the input or output control to which the terminal is to be associated. In Associating Terminals, the left connector terminal is associated with the numeric input control n .


Figure 6.4 Associating Terminals
Repeat for all the input and output controls that are to be associated to the terminals. For the Fibonacci.vi, Connected Terminals shows the right connector terminal associated with the $\mathbf{F i b}(\mathbf{n})$ output terminal.


Figure 6.5 Connected Terminals

### 6.2 Icon Editor

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s.org/licenses/by-sa/4.0/).

Right click on the connector pane and selectEdit Icon... from the pop-up menu. This will bring the icon editor (Figure: Icon Editor). Edit the icon for black and white, 16 -color and 256 -color displays and click OK when completed. Save the G program to complete the function.


Figure 6.6 Selecting Icon Editor


Figure 6.7 Icon Editor

### 6.3 Invoking Functions

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To invoke functions, right click on the Block Diagram window and selectSelect a VI... from the pop-up menu. This will bring a file dialog box. Find the desired function to be part of the program and click OK.


Figure 6.8 Invoking Functions
In the example shown in Fibonacci Series, the Fibonacci series of the first 20 Fibonacci numbers is stored in an array. The numbers are computed by invoking the Fibonacci.vi function.


Figure 6.9 Fibonacci Series

## Chapter 7 Graphs

### 7.1 Waveform Chart

Waveform Charts provide a historical graphical representation of numeric data.
The following example will build a simple $G$ program that will allow you to chart a sine wave as it is being generated on a point-by-point basis using the equation:
$y i=\sin (0.2 x i)$
(9.1)


Figure 7.1 Waveform Chart
Start with a while loop and add into it a Multiply and Sine functions, a numeric constant with value 0.2 and a Boolean control to stop the loop when its value is True. Arrange the diagram to look as in the following Figure Figure 7.2.


Figure 7.2 While Loop For Waveform Chart
To select a waveform chart, right click on the Front Panel window and select Waveform Chart from the Controls »Modern »Graph menu.

Figure 7.3 Selecting Waveform Chart


Figure 7.4
This places the Waveform Chart in the Front Panel window.


Figure 7.5 Waveform Chart in Front Panel window
In the Block Diagram window, make sure that the Waveform Chart terminal is inside the while loop. Wire the output of the Sine function to this terminal.

Notice that Waveform Chart terminal is that of a numeric output.


Figure 7.6 Waveform Chart Terminal
Most modern computers will run this program too fast. Thus, before this program is executed, a delay of 125 milliseconds will be inserted in the while loop. This will allow users to see how the Waveform Chart operates as data samples are plotted in the chard.

From theFunctions »Programming »Timing selectWait Until Next ms Multiple.
This will put the while loop to sleep for the indicated number of milliseconds.


Figure 7.7 Wait Until Next ms Multiple
Drop the Wait Until Next ms Multiple function inside the loop and wire a constant to it with the value
125. This will delay the loop for 125 milliseconds. The final Waveform Chart program is shown in Figure Waveform Chart Program.


Figure 7.8 Waveform Chart Program

The default graphing mode of the Waveform Chart is autoscaling. You will notice the auto-scaling property when the program frst begins to run and the $y$-axis, labeled Amplitude, updates automatically as new numerical values are aggregated and displayed on the chart.


Figure 7.9 Waveform Chart Autoscaling
As the program continues to run, the graph continues to build as per the values associated with the x-axis, labeled Time, which correspond to the index value of the equations.


Figure 7.10 Accumulating Values for the Waveform Chart
As the program continues to run, the autoscaling property also applies to the $x$-axis. Noticed the updated $x$-axis. For this example, the $x$-axis will continue updating so as long as the program is running. This gives the appearance of a scrolling strip chart.


Figure 7.11 Scrolling X-Axis
Stopping and restarting the G program retains the numeric history and continues to aggregate the values for display.


Figure 7.12 Graph History Retained Between Runs
The Waveform Chart options can be easily updated by right clicking on the Waveform Chart and selecting the appropriate option to update from the pop-up menu.

Selecting Properties from this pop-up menu brings up the Waveform Chart dialog window (Figure Figure 7.14).


Figure 7.13 Waveform Chart Pop-Up Menu


Figure 7.14 Waveform Chart Options Dialog Box

### 7.2 Waveform Graph

The Waveform Graph allows numeric arrays to be displayed graphically in the Front Panel window. Similar to the previous example, we will build a simple $G$ program that will allow you to graph a sine wave using the equation:

## $y_{i}=\sin (0.2 x i)$

Figure 7.15
for $\mathrm{i}=0,1,2, \ldots, 99$.


Figure 7.16 Waveform Graph

### 7.2.1 Single Plot

## (1) (0)

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Start by building the following program shown in Figure For Loop Sine Wave.


Figure 7.17 For Loop Sine Wave
Right click on the Front Panel window, select Waveform Graph from the Modern »Graph pop-up menu, and drop it on the Front Panel window.


Figure 7.18 Select Waveform Graph
In the Block Diagram window you will see the Waveform Graph terminal. Wire the Sine function output to the Waveform Graph terminal through the For Loop.


Figure 7.19 Waveform Graph Diagram
Run the program. The resulting graph is shown in Figure Sine Wave Graph.


Figure 7.20 Sine Wave Graph

### 7.2.2 Multiplots

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In this example a sine wave and a noisy sine wave will be plotted. Modify the previous example to add noise to the sine operation as shown in Figure Sine and Noisy Sine Waveforms.


Figure 7.21 Sine and Noisy Sine Waveforms
Add a Build Array operator and wire the output of the Sine function and the multiadd operator containing the sine value plus some random noise between -0.5 and 0.5 to the Build Array operator. Wire the output of the Build Array operator to the Waveform Graph terminal.


Figure 7.22 Bundle Arrays for Multiplotting
You can continue adding 1D arrays to be multiplotted into a single Waveform Graph. Run the program. The multiplot result is shown in Figure Multiplot.


Figure 7.23 Multiplot

### 7.3 XY Graph

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s.org/licenses/by-sa/4.0/).

The XY Graph plots x vs. y numeric values contained in arrays.


Figure 7.24 XY Graph
The example shown in Figure Spiral G Program generates the spiral shown in Figure Fi gure 7.24.


Figure 7.25 Spiral G Program

## Chapter 8 Interactive Programming

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The heart of interactive programming in G is the while loop. Any input control within the while loop can be modified from the Front Panel window at run time to provide seamless interaction with the G program.

Interactive
G Program


Figure 8.1 Creating Interactive Programs
In the Front Panel window, from the Functions »Modern »Numeric select the vertical pointer slide. From the Functions »Modern »Graph select Waveform Chart.

| Modern <br> $L_{\text {Numeric }}$ |  |  |
| :---: | :---: | :---: |
| 51.23 | 1.23 | $\sqrt{12: 00}$ |
| Numeric Control $\begin{aligned} & 12: 00 \\ & 11 / 07 \end{aligned}$ | Numeric Indic... $\begin{gathered} 10^{-} \\ 5- \\ 0- \end{gathered}$ | Time Stamp C... |
| Time Stamp I. . . | Vertical Fill Slide | Verical Point... |

Figure 8.2 Vertical Pointer Slide and Waveform Chart


Figure 8.3 Vertical Pointer Slide and Waveform Chart
Re-label the vertical pointer slide as Amplitude and the waveform chart as Sine Wave. Re-arrange to GUI to look like the figure below.


Figure 8.4 Slide \& Waveform Chart in Front Panel window
Right click on Sine Wave and select Properties from the pop-up menu.


Figure 8.5 Selecting Chart Properties
Select the Scales tab and change Maximum to 1023. Sine Wave will display 1024 samples.


Figure 8.6 X-Axis Maximum
Click on the down arrow located to the right of Time (XAxis) and select Amplitude (YAxis).


Figure 8.7 Selecting Y-Axis
De-selectAutoscale and change the Minimum and Maximum values to-10 and $\mathbf{1 0}$. ClickOK.


Figure 8.8 De-Selecting Autoscale
Rearrange Amplitude and Sine Wave terminals and finish the program as shown in Figure Figure 8.9. Scroll the mouse pointer over the Loop Control...


Figure 8.9 Interactive Sine Wave Diagram


Figure 8.10 Loop Condition
And right click on the Loop Control and from the pop-up menu select Create Control. A stop terminal is created.


Figure 8.11 Create Control


Figure 8.12 Interactive G Program
With the corresponding stop Boolean input control. Save the G program asInteractivity.vi.


Figure 8.13 Interactive Program
Run the G program.


Figure 8.14 Interactive Program
While the program is running, change the Amplitude and watch the graph update to reflect the interactive changes.


Figure 8.15 Interactive Program
To end the G program, simply click on the stop button.


Figure 8.16
Congratulations. You have successfully completed and executed your first interactive G program.

## Chapter 9 Parallel Programming

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In 1985, by design, $G$ was developed to address and simplify parallel programming. If you have gone through the examples in this book, you have already developed various parallel programs.

In the following example, we will develop a simple program where interactivity and parallelism are part of the program.


Figure 9.1 Select Diagram for Parallel Programming
From the menu select Edit »Copy.


Figure 9.2 Copy Selected Diagram
Create a copy of the while loop and its contents by selecting Edit »Paste. Organize the diagram as shown in the figure below.


Figure 9.3 Paste Diagram
Go the Front Panel window and organize the input and output controls as shown in the figure below.


Figure 9.4 Parallel G Program
You have just completed your first parallel interactive program using G. Save the program, run it and interact with it.


Figure 9.5 Parallel Interactive G Program
To end this program click on the stop and stop 2 terminals.

## Chapter 10 Multicore Programming



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If you have written parallel programs in $G$ and have a multicore computer, CONGRATULATIONS!!! You have been successfully developing interactive parallel programs that execute in multicore PC processors.


Figure 10.1 Interactive Multicore G Program
The following sections discuss some multicore programming techniques to improve the performance of G programs.

### 10.1 Data Parallelism

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Matrix multiplication is a compute intensive operation that can leverage data parallelism. Figure Data Parallelism shows a G program with 8 sequential frames to demonstrate the performance improvement via data parallelism.


Figure 10.2 Data Parallelism

The Create Matrix function generates a square matrix based of size indicated by Size containing random numbers between 0 and 1 . The Create Matrix function is shown in Figure Creating a Square Matrix.


Figure 10.3 Creating a Square Matrix
The Split Matrix function determines the number of rows in the matrix and shifts right the resulting number of rows by one (integer divide by 2). This value is used to split the input matrix into the top half and bottom half matrices. The Split Matrix function is shown in Figure Split Matrix into Top \& Bottom.


Figure 10.4 Split Matrix into Top \& Bottom

| Sequence <br> Frame | Operation Description |
| :--- | :--- |
| First Frame | Generates two square matrices initialized with random <br> numbers |
| Second Frame | Records start time for single core matrix multiply |
| Thrid Frame | Performs single core matrix multiply |
| Fourth Frame | Records stop time of single core matrix multiply |
| Fifth Frame | Splits the matrix into top and bottom matrices |
| Sixth Frame | Records start time for multicore matrix multiply |
| Seventh <br> Frame | Performs multicore matrix multiply |
| Eighth Frame | Records stop time of multicore matrix multiply |

The rest of the calculations determine the execution time in milliseconds of the single core and multi-core matrix multiply operations and the performance improvement of using data parallelism in a multicore computer.

The program was executed in a dual core 1.83 GHz laptop. The results are shown in Figure Data Parallelism Performance Improvement. By leveraging data parallelism, the same operation has nearly a $2 x$ performance improvement. Similar performance benefts can be obtained with higher multicore processors


Figure 10.5 Data Parallelism Performance Improvement

### 10.2 Task Pipelining

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A variety of applications require tasks to be programmed sequentially and continually iterate on these tasks. Most notably are telecommunications applications require simultaneous transmit and receive. In the following example, a simple telecommunications example illustrates how these sequential tasks can be pipelined to leverage multicore environments.

Consider the following simple modulation -demodulation example where a noisy signal is modulated transmitted and demodulated. A typical diagram is shown in Figure Sequential Tasks.


Figure 10.6 Sequential Tasks
Adding a shift register to the loop allows tasks to be pipelined and be executed in parallel in separate cores should they be available. Task pipelining is shown in Figure Pipelined Tasks.


Figure 10.7 Pipelined Tasks
The program below times the sequential task and the pipelined tasks to establish its performance improvement when executed in multicore computers.


Figure 10.8 Task Pipelining Program Example

Figure Pipelining Performance Improvement shows the results of running the above $G$ program in a dual core 1.8 GHz laptop. Pipelining shows nearly $\mathbf{2 x}$ performance improvement.

| Sequential |  |
| :--- | :--- |
| 5953 |  |
| Pipelined |  |
| 3156 | 1.88625 |

Figure 10.9 Pipelining Performance Improvement

### 10.3 Pipelining Using Feedback Nodes

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Feedback Nodes provide a storage mechanism between loop iterations. They are programmatically identical to the Shift Registers. Feedback Nodes consist of an Initializer Terminal and the Feedback Node itself (see Figure Feedback Node).


Figure 10.10 Feedback Node
To add a Feedback Node, right click on the Block Diagram window and select Feedback Node from the Functions »Programming »Structures pop-up menu. The direction of the Feedback Node can be changed by right clicking on the node and selecting Change Direction.


Figure 10.11 Feedback Node Direction
The diagram shown in Figure Pipelining with Feedback Node is programmatically identical to the diagram in Figure Pipelined Tasks.


Figure 10.12 Pipelining with Feedback Node
Similarly, the diagram in Figure Pipelining Tasks with Feedback Nodes is programmatically identical to that in Figure Task Pipelining Program Example.


Figure 10.13 Pipelining Tasks with Feedback Nodes

## Chapter 11 Input and Output

### 11.1 Writing to File

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Consider the function in Figure Figure 11.1 where a set of numbers in a onedimensional array represents the resulting noisy signal is to be written to a file. This section will outline the steps required to create files.


Figure 11.1 Noisy Signal Function
Create a new G program, right click in the G programming window and select File Dialog from the Functions »Programming »File I/O »Advanced Functions menu. Drag and drop the File Dialog function onto the G programming window.

- Programming
$L_{\text {File I/O }}$
${ }^{\text {L }}$ Advanced File Functions


Get File Position Get File Size Set Type \& C... File Dialog
Figure 11.2 File Dialog
The Configure File Dialog dialog box automatically appears to configure the function. Accept the default configuration shown in Figure Figure 11.3 to create a single file by clicking the OK button.


Figure 11.3 Configure File Dialog

The resulting diagram after closing the configuration dialog box is shown in . Optionally, right click on File Dialog and select View As Icon from the pop-up menu. This will save some real estate in the G programming window.


Figure 11.4 G File Dialog


Figure 11.5 View As Icon
From the Functions »Programming »File I/O menu select Open/Create File, Write Binary File and Close File functions.


Figure 11.6 File Input and Output Operators
Arrange the File I/O operations as shown in Figure Figure 11.7.
File Dislog


Figure 11.7 Open, Write and Close File Diagram
Right click on the operation (0:open) terminal of the Open/Create File function (highlighted in Figure File Create Operation).


Figure 11.8 File Create Operation
Select Create » Constant from the pop-up menu.


Figure 11.9 Create Operation Constant
Arrange the diagram to look as in Figure Figure 11.10.


Figure 11.10 Operation Constant
Click on the down arrow in the operation constant just created and select open or create from the pop-up menu.

| $\checkmark$ open |
| :--- |
| replace |
| create |
| open or create |
| replace or create |
| replace or create with confirmetion |

Figure 11.11 Open or Create File Operation
The resulting updated operation constant value is shown in Figure Figure 11.12.


Figure 11.12 Create File to Write
Repeat the process to create a constant for theaccess (0:read/write) terminal (highlighted in Figure Figure 11.13).


Figure 11.13 File Access Mode
Set the constant to write-only. Re-arrange the block diagram to look like the diagram shown in Figure Figure 11.14. At this point, the file is set to create a new file for writing.


Figure 11.14 Write Only Mode
Get the Noisy Signal function and wire its output data to the Data terminal of the Write to Binary File function.


Figure 11.15 Writing Binary Data
Complete the diagram by connecting the Open, Write and Close file operations as shown in Figure Figure 11.16.


Figure 11.16 Writing to File G Program
When this G program is executed, the standard file dialog box appears. Name the file to be written signal.dat.


Figure 11.17 Create File Dialog Box

Once the program completes executing, the signal.dat file is created and located in the location indicated by the path selected.


Figure 11.18 Data File signal.dat

### 11.2 Reading From Files

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The signal.dat file created in the previous example will be used to read data from a file. As in the previous example, select the File Dialog, Open/Create File, Read from Binary File and Close File functions.


Figure 11.19 Operators to Read Files
Create constants by right clicking on the operation (0:open) and access (0:read/ write) terminals of the Open/Create File operation. Set the constants toopen andread-only respectively (see Figure Figure 11.20).


Figure 11.20 Set to Open and Read-Only
Similar to creating arrays, drop an array constant in the G diagram, drop a numeric constant onto the array constant and set the data type representation to double. Wire this array constant to the data type terminal of the Read from Binary File function as shown in Figure Figure 11.21.


Figure 11.21 Data Type to Read
In the Front Panel window, drop a Waveform Graph.


Figure 11.22 Graph for Data to be Read
With the data type specified, wire thedata terminal of the Read from Binary File function to the Waveform Graph terminal as shown in Figure Figure 11.23.


Figure 11.23 Data to be Read
Complete the program by wiring refnum and error terminals of the Open/Create File, Read from Binary File and Close File functions as shown in Figure Figure 11.24.


Figure 11.24 Read Binary Data G Program
When this program is executed, a fle dialog box appears. Select the signal.dat file and click OK.


Figure 11.25 Select Binary File to Read From
The binary data in signal.dat is read and plotted in a Waveform Graph. The result is shown in Figure Figure 11.26.


Figure 11.26 Read Data Graphed

